MOTIVATION

Reference frames and coordinate systems are exercise in physics: provide the point of view fram which obsenvations are carried out. Not exactly the some, définitions in the litertere differ. For us: Set of vowebles associated to a PHYSICAL SYSTEM, that we can use to describe other plugsical systems recohorably. Since 1364: QRFS in < QG (Dewith) at (Alcanov, Susskind) Necessity of cousidering RFS proceided to physical systems. aI/ A and B, Key need to share information but do not know how they are oriented relative to each other; they want to edentify the "2" direction with a big spin, where has some quantum uncertainty associated to it. aG if gravity is quantum => no specetime => no classical RF. ön GR it does not make sense to cocolise a single system => öneed a playsical system to cocolise another playsical system. Need to consider REATUE Cocolisation between two making quouter systems ier whoken replaces spacetime (Also more teluical reasons related to the quantisation of gravity as a gauge keavy, see Daniele's lectures) are particular approach to aRFs: PERSPECTIVAL/FOUNDATIONAL Research programme: many gren questions (e.g. how to include the observer, bridge with granty / aI, etc...)

In recent years the approaches started to came together.





Dynamical Caus

The QRF also has a House Assume & receitance $H_{AB}^{(c)}$, $e_{AB}^{(c)}$ => its $\frac{d\hat{e}_{AB}^{(c)}}{dt} = [\hat{H}_{AB}^{(c)}, \hat{e}_{AB}^{(c)}]$ ê la = ŝ ê la ŝt $\hat{H}_{Bc}^{(A)} = \hat{S}\hat{H}_{AB}^{(C)}\hat{S}^{\dagger} + i\hbar \frac{d\hat{S}}{dt}\hat{S}^{\dagger}$ $\hat{\mathcal{E}}$ is a symmetry if $\hat{\mathcal{H}}_{BC}^{(A)}$ lies the same functional form as $\hat{\mathcal{H}}_{AB}^{(c)}$ but with all colores $A \leftarrow > C$ In particular, we have sep. of EXT. GAL. TRANSF. $\hat{S}_{i} = e^{i\frac{1}{5}H_{c}^{(A)}t} \underbrace{\hat{P}}_{Ac} \left(e^{i\frac{1}{5}e_{a}\sqrt{\frac{2}{2}}\hat{D}_{A}} \right) \hat{U}_{i} (t) e^{i\frac{1}{5}\hat{H}_{A}t}$ Û.(t): clossical RF transf where parameters -> operators an A $\hat{D}_{A} = \hat{x}_{A}\hat{p}_{A} + \hat{p}_{A}\hat{x}_{A}$: arely recently in some cases (boosts + accel.) $\mathcal{G}_{AC}^{(\sigma)}$, $\mathcal{G}_{AC}^{+(\sigma)} = -\frac{(ee_A}{(ee_C}) \hat{n}_C = \frac{1}{2}$ momente trouss, ier scech a way kief keeg are cossiler connected to the rel vel. INTUITION About TRANSF. (especially Houself.) $\hat{S}_{b} = e^{\frac{i}{\hbar}\frac{\hat{M}_{c}}{2mc}t} \hat{S}_{Ac} e^{\frac{i}{\hbar}\frac{\hat{p}_{A}}{mc}} \hat{S}_{B} e^{\frac{i}{\hbar}\frac{\hat{p}_{A}}{2mc}t} \times A^{(a)}_{Ac}$ $H_{AB}^{(c)} = \frac{\hat{P}_{A}}{2ma} + \frac{\hat{P}_{B}}{2ma}$ \rightarrow $H_{Bc}^{(A)} = \frac{\hat{\eta}_{B}^{2}}{\hat{\eta}_{B}} + \frac{\hat{\eta}_{C}^{2}}{\hat{\eta}_{C}}$ SYNHETRY !

QRF transf. May seeme strange, but king form a graup! BALLESTEROS, GIACONENNI, GUBITOSI QUANTUM (2021) $\hat{P}_{AB} = \hat{X}_{A} \otimes \hat{P}_{B}$; $\hat{K}_{AB} = \frac{\hat{P}_{A}}{ue_{A}} \otimes \hat{G}_{B}$; $\hat{D}_{AIB} = \frac{1}{2} (\hat{X}_{A} \hat{P}_{A} + \hat{P}_{A} \hat{X}_{A})_{IB}$, ecc. $\hat{L}\hat{A}_{i}$, \hat{A}_{i}] = $\hat{g}_{ijk} \hat{A}_{k}$ -> group leas * generalars, not a known group Emportant because J care compose transf and remain in the features

what one QRF; useful for?

- Degine vest frame of a quantum system * Sten-Geradel FG, CASTRO-RUIZ, BRUKNER, PRL (2013) * Ref. Bell ing. STREITER, FG, BRUKNER, PRL (2021) * Deppler effect FG, CASTRO-RUIZ, BRUKNER, NAT. CONM. (2013) * Decay role FG, KEMPF, PRD (2022)

- Nou- classical spacetime ~ 0 see aller Certeurs!



PERSPECTIVE NEUTRAL APPROACH TO QRFS

VANRIETVEZDE, HÖHN, GIACONINI, CASTRO-RUIZ, QULNTUN (2020) Enspired to GR. There is a description with no plugsical counterpart, but that can be mapped to one in which any relational d.o.f. oue meaningful. Redendancy ~ diffeo invariance in GR. N ponticle dagrangian (m:=1) $\mathcal{L} = \frac{4}{3} \mathcal{Z}_{i} \dot{q}_{i}^{2} - \frac{1}{30} \left(\mathcal{Z}_{i} \dot{q}_{i}^{2} \right)^{2} - V\left(\left\{ q_{i} \cdot q_{i} \right\} \right)$ ECH : ouly the motion rel. to an contrubutes $\frac{\partial d}{\partial q_i} = \dot{q}_i - \frac{1}{D} \frac{z_i}{2} \dot{q}_i = p_i =) Z_i p_i = 0 \quad \text{CH momentum is zero} \\ Lo dynamical constraint}$ EOH $q_i - \frac{1}{2} \frac{2}{4} \frac{q_i}{q_i} + \frac{\partial V}{\partial q_i} = 0$ REDUNDANCY Cousiskurry cleak: $Z_i q_i - Z_j q_j + Z_i \frac{\partial V}{\partial q_i} = Z_i \frac{\partial V}{\partial q_i} = 0$ for a control potential potential if we colleulate the Hour. we find (Legendre transf.) $H = Z_{c} \frac{P_{c}}{2} + V(...)$ but we know Kick, ou kee EOH Zipiso Hence & com with E : CONSTRAINT H = Z: $\frac{p_i^2}{2i}$ + V(...) + $d(Z:p_i)$ => does not change the physics LO LAGRANGE HULTIPLIER On the solutions of the EOH E 20 (weak equality) Great & as a deguarrical raciable. It is rudep. of Pr, lience $d = \frac{\partial H}{\partial P_A} = 0$ (d does not evolve). We also have $\dot{P}_{A} = \{P_{A}, H\} = -\mathcal{E} = 0$ V because $P_{A}(A, \dot{A})$

Finally, E has to be presented by the deguances E = {E, H} = 0 by coustinctions in our cose If this does not happen, we need to add whatever we find as an additional constraint whe we find no contradiction. DIRAC QUANTISATION qu > qu ; pu > pu ; Equipise in sig =DThun enface the coustiont. $\hat{H} = Z_{i} \frac{\hat{P}_{i}^{2}}{2} + V(\{\hat{q}_{i} - \hat{q}_{i}\}) + \lambda \hat{\mathcal{E}}, \quad \hat{\mathcal{E}} = Z_{i} \hat{\rho}_{i}$ we know kist É vanishes au kne schechaus of the EON. What does it mean in aT? any allowed stokes are knoses. I. ÊIY)pg = 0 We have two Hills. sp. KKin -> oll states Hph -> only shoke s.t. EIX)pe = 0 Each Hills. sp. is endowed with a scalar product, in pronciple diff.! Z: p: has coutimous spectrum, in part. around zero =) we have to find a new scalar product that makes the staks well-reamplised are Hperys IMPROPER PROJECTOR $S(\hat{P}) = \frac{1}{2\pi} \int ds e^{is\hat{P}}$ $S(\hat{P}): H. - V$ $\hat{p} = Z_i \hat{p}_i$ S(P): Hkin -> Hperys <414>pengs = <415(\$)147kin How do it reduce to the persp. of a specific arr? Assemme 3 particles A, B, C.

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